

FACTORING, ROOT FINDING, AND SEVERAL OTHER THINGS

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- Multivariate Polynomial Factoring
 - Background and Motivation.
 - Factoring Algebraic Branching Programs.
- Multivariate Factoring and PIT.

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Multivariate Polynomial Factoring: Background

- We encounter integer and polynomial factoring in school.
- Polynomials can be factored in polynomial time.
- Factor $f(x) \in \mathbb{Q}[x]$ using [LLL algorithm](#) in deterministic polynomial time.
- Factor $f(x) \in \mathbb{F}_q[x]$ using Berlekamp's algorithm.

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- Polynomials are often easier cases than integers.
- **Squarefree**: Test if a given integer or polynomial has a factor that repeats.
- For integers, no polynomial time algorithm for this is known.
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KRONECKER-SCHUBERT REDUCTION

- Suppose $f(x_1, \dots, x_n) = g(x_1, \dots, x_n)h(x_1, \dots, x_n)$.
- Degree of each variable in $f(x_1, \dots, x_n)$ is $\leq d$.
- Apply Kronecker substitution $\phi : x_i \mapsto z^{D^{i-1}}$ where $D = d + 1$.
- Each monomial in f uniquely maps to a monomial in $\phi(f)$. Thus, we can invert the map ϕ .

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- If $f = gh$, then $\phi(f) = \phi(g)\phi(h)$.
- Factorize $\phi(f)$ into univariate irreducible factors.
- Though g is irreducible, $\phi(g)$ may not be irreducible.
- Product of a subset of the factors of $\phi(f)$ would correspond to $\phi(g)$.
- Try all subsets. Apply inverse Kronecker and test divisibility.
- Time complexity: Exponential in degree in worst-case (even for bivariate).

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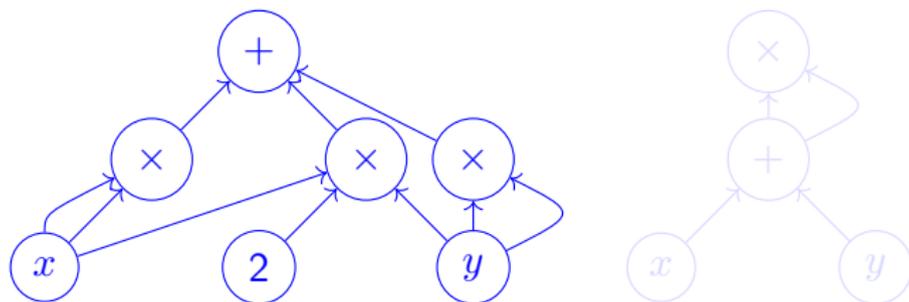
- Kaltofen (1982): Efficient reduction of bivariate to univariate factoring.
- Tools: Newton iteration/ Hensel lifting, Linear System Solving.
- We have to define the size of input and output polynomials in the multivariate setting to talk about time complexity.

REPRESENTING MULTIVARIATE POLYNOMIALS

- **Dense:** List all the coefficients of $\binom{n+d}{d}$ many monomials up to degree d .
- **Sparse:** List only the monomials with nonzero coefficients.
Eg. $x_1^2 + x_2x_3 + 5x^4$.
- **Formula:** $(1 + x_1)(1 + x_2)x_3 - (1 + x_1)^2$. Reuse of computation **not** allowed. Structurally, looks like a tree.
- Straight-Line Programs or Arithmetic Circuits.

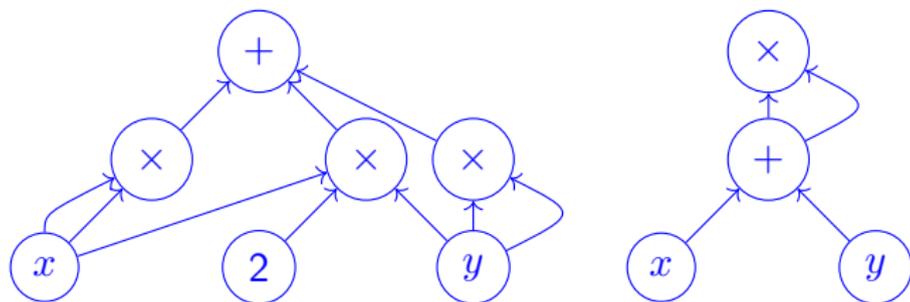
Arithmetic circuits

Two circuits for computing $x^2 + 2xy + y^2$



Size: Total number of nodes or edges.

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FACTORIZATION OF A POLYNOMIAL

Let f be a polynomial of degree d that has size s in some model.

$$f(x_1, \dots, x_n) = \prod_{i=1}^m f_i^{e_i}$$

Let f_i 's be its irreducible factors over \mathbb{F} .

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- Let \mathcal{C} be a class of polynomials.
- Closure under multiplication: $f, g \in \mathcal{C} \implies f \times g \in \mathcal{C}$.
- Closure under factoring: If $f \times g$ is in \mathcal{C} , are f, g also in \mathcal{C} ?
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 $x^d - 1 = (x - 1)(1 + x + \dots + x^{d-1})$.
- Sparsity of factors can be superpolynomial wrt input polynomial's sparsity.
- **Kaltofen 1986:** If size denotes arithmetic circuit size, $g \mid f \implies \text{size}(g) \leq \text{POLY}(\text{size}(f), \text{deg}(f))$.
- **Goal:** Extend Kaltofen's result for factors of formulas, constant depth circuits, algebraic branching programs (ABPs), etc.

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- Multivariate Polynomial Factoring has applications in coding theory and various other problems.
- Helps to bridge two central questions in algebraic complexity: VP vs VNP and polynomial identity testing (PIT).
- Kabanets and Impagliazzo (2003): Exponential **lower bound** for arithmetic circuits \implies Quasi-poly blackbox **deterministic PIT** for circuits.
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- Dutta, Saxena, S (2018): If we take formula/ABP, $g \mid f \implies \text{size}(g) \leq \text{poly}(\text{size}(f), d^{O(\log d)})$.
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Factorization of Arithmetic Branching Programs

Theorem (S, Thierauf, 2020)

Let polynomial $p(\vec{x})$ over \mathbb{F} have ABP-size s .

All factors of p have ABP-size $\text{POLY}(s)$

Algorithm: Factors can be efficiently constructed in randomized polynomial time.

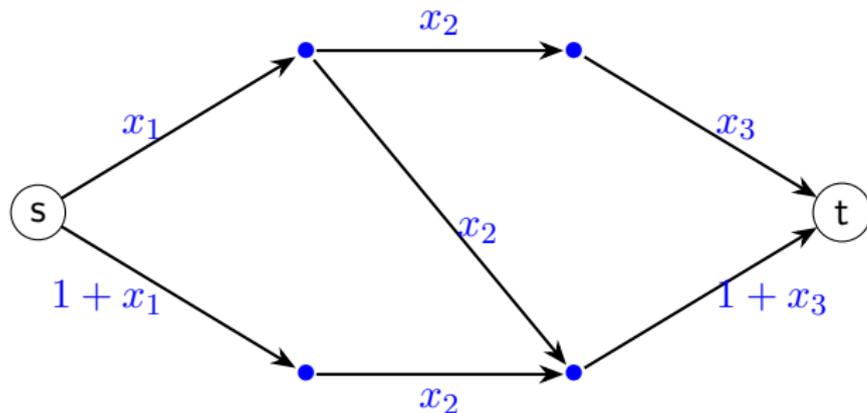
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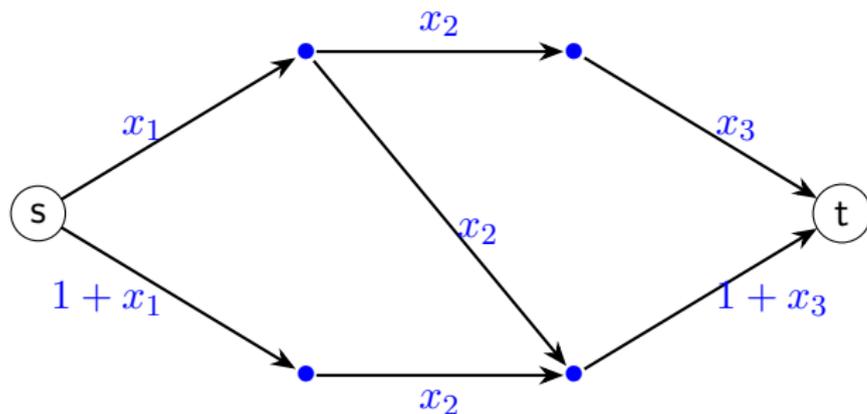
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The polynomial computed by the above ABP is

$$x_1x_2x_3 + x_1x_2(1 + x_3) + (1 + x_1)x_2(1 + x_3).$$

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Arithmetic Formula \leq ABP \leq Arithmetic Circuit

DET: compute determinant of $n \times n$ matrices

- DET \in NC² [Csanky-Faddeev-LeVerrier 1976]
[Berkowitz-Samuelson 1985, Chistov 1985]
- DET by poly(n)-size ABPs [Mahajan-Vinay 1997]

Consequence

Poly-size ABPs can compute solutions of linear systems over $\mathbb{F}(x_1, \dots, x_n)$.

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Techniques for factorization

Newton Iteration

[Oliveira 2016, Dutta, Saxena, S 2018]

Factoring \leq root approximation in power series

- $p(\mathbf{x}, y)$ has factor $y - q(\mathbf{x}) \iff p(\mathbf{x}, q(\mathbf{x})) = 0$
- approximate root via Newton iteration

$$y_{t+1} = y_t - \frac{p(\mathbf{x}, y_t)}{p'(\mathbf{x}, y_t)}$$

- $\log d$ iterations leads to $d^{\log d}$ -size ABPs

Hensel Lifting

(Kurt Hensel, 1861 - 1941)

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Factoring via Hensel Lifting

After preprocessing: $f(x, y)$, 2-variate, degree d , *monic* in x
(i.e. highest x -power has constant coefficient)

Goal: Compute g s.t. $f = g h$

① Initial step: Factorize univariate polynomial $f(x, 0)$

- $f(x, 0) = g_0(x) h_0(x)$
- Equivalently: $f(x, y) \equiv g_0(x) h_0(x) \pmod{y}$

② **Lifting:** compute $g_1(x, y), h_1(x, y)$

- $f \equiv g_1 h_1 \pmod{y^2}$

Iterate lifting $t = O(\log d)$ times: $f \equiv g_t h_t \pmod{y^{2^t}}$

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One can show: for some polynomial h'_t

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- g_t known, but g and h'_t unknown
- Set up linear system in unknown coefficients of g and h'
- **Jump Step:** Right choice of $t \implies$ we get g , **without any mod!** Can be proved using resultants.

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Main difference to earlier liftings

Start with g_0, h_0 monic

- standard Hensel Lifting maintains g_k, h_k monic, for all k
- simplified version gives up monicness: **saves a division**
- ABP-size grows by a constant factor in each iteration
 \implies overall size $\text{poly}(c^{\log d}, s) = \text{poly}(s)$
- Crucial technical part: Jump Step still works!

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- Let \mathcal{R} be a commutative ring with 1 and $\mathcal{I} \subseteq \mathcal{R}$ be an ideal.
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 - (factorization) $f \equiv gh \pmod{\mathcal{I}}$
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- Then g', h' is lift of g, h w.r.t. f if it satisfy the following.
 - (Better factorization) $f \equiv g'h' \pmod{\mathcal{I}^2}$,
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NONMONIC LIFTING IS CHEAPER

- Compute the following.
- $e = f - gh$
- $g' = g + be$ and $h' = h + ae$
- $c = ag' + bh' - 1$
- $a' = a(1 - c)$ and $b' = b(1 - c)$.
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MONIC VERSION OF HENSEL LIFTING

- Assume f, g, h are polynomials monic in x .
- Additionally compute polynomials q and r such that $g' - g = qg + r$, where $\deg_x(r) < \deg_x(g)$.
- $\hat{g} = g + r$ and $\hat{h} = h'(1 + q)$ are a monic lift of g, h w.r.t. f .
- Advantage: We can avoid the linear system-solving step if we start monic lifting from $g(x, 0)$ and $h(x, 0)$!
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Lemma (Actual factor vs lifted factor)

$g \equiv g_t h'_t \pmod{y^{2^t}}$ for some polynomial h'_t .

Proof Idea

Inductively apply Hensel lifting to both f and factor g starting from $f = g_0 h_0 \pmod{y}$ and $g = g_0 h'_0 \pmod{y}$ respectively.

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- We want to compute g from the Eqn. $g \equiv g_t h'_t \pmod{y^{2^t}}$.
- Here g_t is known but both g and h'_t are unknown. We know the degree upper bounds of g, g_t, h'_t .
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FACTOR RECONSTRUCTION VIA LINEAR SYSTEM

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SOLUTION OF LINEAR SYSTEM GIVES FACTOR

- Let \tilde{g} be a least degree monic polynomial that satisfies $\tilde{g} = g_t \tilde{h} \pmod{y^{2^t}}$ for some \tilde{h} . We prove that $\tilde{g} = g$.
- First prove that \tilde{g} and the factor g have nontrivial gcd by showing that their Resultant is zero.
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- View g_t and w as polynomials in y with coefficients in x .
Suppose $g_t = c_0(x) + c_1(x)y + \dots + c_{d'}(x)y^{d'}$.
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- Thus $g_t w \pmod{y^{2^t}}$ is not free of x . Contradiction. Thus, $r(y)$ must be $0 \pmod{y^{2^t}}$. If $2^t \geq 2d^2 + 1$, then $r(y) = 0$. QED.

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- Now, $g_t \equiv g_0 \pmod{y}$, so $c_0(x) = g_0(x)$, a nonzero poly in x .
- The least power of y in $g_t w$ has coefficient $g_0(x)w_j(x)$, a nonzero polynomial in x .
- Thus $g_t w \bmod y^{2^t}$ is not free of x . Contradiction. Thus, $r(y)$ must be $0 \bmod y^{2^t}$. If $2^t \geq 2d^2 + 1$, then $r(y) = 0$. QED.

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- Create a new polynomial $\hat{f}(x, y, z) = f(x, yz_1, \dots, yz_n)$
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Factorization and PIT

- Test if $g(x_1, \dots, x_n)$ divides $f(x_1, \dots, x_n)$.
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SPARSE DIVISIBILITY TESTING

- Whether a linear polynomial divides a sparse polynomial can be tested in polynomial time.
- $f(x_1, \dots, x_n)$ is divisible by $x_1 - \ell(x_2, \dots, x_n)$ iff $f(\ell, x_2, \dots, x_n) = 0$.
- **Semidiagonal model:** $\sum m_i \ell^{e_i}$ where m_i is a monomial and ℓ are linear polynomials [Saha-Saptharishi-Saxena 2010].
- Testing if a quadratic polynomial divides a s -sparse polynomial in $s^{\log s}$ time [Forbes 2015]. Reduces to PIT of sums of monomials times powers of quadratics.
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- Given a black box computing a multivariate polynomial f , black boxes of the irreducible factors of f can be computed in randomized polynomial time [Kaltofen-Trager 1991].
- **Dimension reduction:** Randomly project to bivariates.
- This works due to an effective version of Hilbert's irreducibility theorem.
- If $f(x, z_1, \dots, z_n)$ is irreducible, then $f(x, \beta_1 + \alpha_1 y, \dots, \beta_n + \alpha_n y)$ is irreducible with high probability if β_i, α_i picked at random.
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- Over \mathbb{Q} , this can be done.
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